

LINEAR INTEGRATED CIRCUIT

SARARA

DIP-16

SOP-16

7CH DARLINGTON SINK DRIVER

DESCRIPTION

The UTC ULN2003 are high-voltage, high-current darlington drivers comprised of seven NPN Darlington pairs.

All units feature integral clamp diodes for switching inductive loads.

Applications include relay, hammer, lamp and display (LED) drivers.

FEATURES

*Output Current (S *High Sustaining V

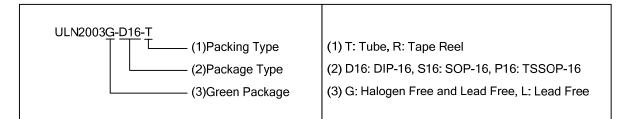
*Output Clamp Dio

*Inputs Compatible

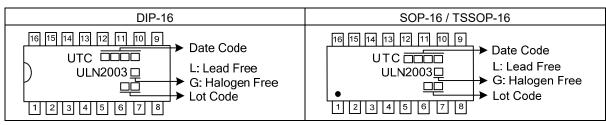
ORDERING

		TSSOP-1				
• .	t): 500mA (Max.)					
odes	out: 50V (Min.)					
e With Vario	us Types Of Logic					
g inform	/IATION			_		
Ordering	Number	Dookogo	Decking			
ee	Halogen Free	Package	Packing	l		

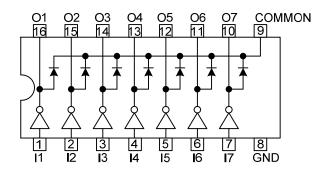
Number	Dookogo	Packing	
Halogen Free	гаскауе		
ULN2003G-D16-T	DIP-16	Tube	
ULN2003G-S16-R	SOP-16	Tape Reel	
ULN2003G-P16-R	TSSOP-16	Tape Reel	
	Halogen Free ULN2003G-D16-T ULN2003G-S16-R	Halogen FreePackageULN2003G-D16-TDIP-16ULN2003G-S16-RSOP-16	



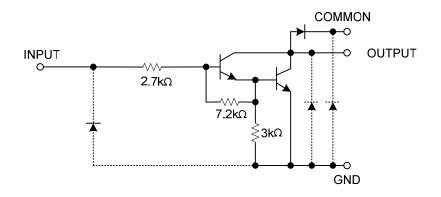
MARKING



PIN CONNECTION



BLOCK DIAGRAM



Note: The input and output parasitic diodes cannot be used as clamp diodes.



LINEAR INTEGRATED CIRCUIT

■ **ABSOLUTE MAXIMUM RATINGS** (T_A=25°C, unless otherwise specified)

PARAMETER		SYMBOL	RATING	UNIT
Output Sustaining Voltage		V _{OUT}	-0.5 ~ 50	V
Input Voltage		VIN	-0.5 ~ 30	V
Clamp Diode Reverse Voltage		V _R	50	V
Output Current		I _{OUT}	500	mA / ch
Clamp Diode Forward Current		I _F	500	mA
	DIP-16	PD	1.47	W
Power Dissipation	SOP-16		1.25 (Note2)	W
TSSO			0.62	W
Junction Temperature		ТJ	+150	°C
Operating Temperature		T _{OPR}	-40 ~ +85	°C
Storage Temperature		T _{STG}	-55 ~ +150	°C

 Notes: 1. Absolute maximum ratings are those values beyond which the device could be permanently damaged. Absolute maximum ratings are stress ratings only and functional device operation is not implied.
2. On PCB (Test Board: JEDEC 2s2p)

■ **RECOMMENDED OPERATING CONDITIONS** (T_A=-40~+85°C, unless otherwise specified)

CHARACTERISTIC		SYMBOL	TEST CONDITIONS		MIN	TYP	MAX	UNIT
Output Sustaining Voltage		V _{OUT}			0		50	V
	DIP-16	Ι _{Ουτ}	T _{PW} = 25ms	Duty=10%	0		415	mA/ch
				Duty=50%	0		150	
Output Current	SOP-16			Duty=10%	0		375	
Output Current			T _A = 85°C	Duty=50%	0		135	
	T000D 40			Duty=10%	0		150	
	TSSOP-16			Duty=50%	0		30	
Input Voltage		V _{IN}			0		24	V
Input Voltage (Output On)		V _{IN (ON)}	I _{OUT} = 400mA		2.8		24	V
Input Voltage (Output Off)		V _{IN (OFF)}			0		0.7	V
Clamp Diode Reverse Voltage		V _R					50	V
Clamp Diode Forward Current		I _F					350	mA
	DIP-16		T _A = 85°C				0.76	W
Power Dissipation	SOP-16	PD	T _A = 85°C (Note)				0.65	W
	TSSOP-16		T _A = 85°C				0.32	W

Note: On PCB (Test Board: JEDEC 2s2p)



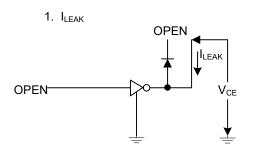
CHARACTERISTIC	SYMBOL	TEST CIRCUIT	TEST C	ONDITIONS	MIN	TYP	MAX	UNIT
		4	V _{CE} =50V, T _A	_=25°C			50	μA
Output Leakage Current	I _{LEAK}	1	V _{CE} =50V, T _A	,=85°C			100	μA
Collector Emitter Seturation			I _{OUT} =350mA	, Ι _{IN} =500μΑ		1.3	1.6	V
Collector-Emitter Saturation	$V_{CE(SAT)}$	2	I _{OUT} =200mA	, Ι _{IN} =350μΑ		1.1	1.3	V
Voltage			I _{OUT} =100mA	, Ι _{IN} =250μΑ		0.9	1.1	V
DC Current Transfer Ratio	h _{FE}	2	V _{CE} =2V, I _{OUT}	_r =350mA	1000			
Input Current (Output On)	I _{IN (ON)}	3	V _{IN} =2.4V, I _{OI}	_{UT} =350mA		0.4	0.7	mA
Input Current (Output Off)	I _{IN (OFF)}	4	Ι _{ουτ} =500μΑ,	T _A =85°C	50	65		μA
Input Voltage (Output Op)	V	5	V -2V	I _{OUT} = 350 mA			2.6	V
Input Voltage (Output On)	V _{IN(ON)}	5	V _{CE} =2V	I _{OUT} = 200 mA			2.0	V
Clamp Diada Bayaraa Current		6	V _R =50V, T _A =	=25°C			50	μA
Clamp Diode Reverse Current	I _R	0	V _R =50V, T _A =	=85°C			100	μA
Clamp Diode Forward Voltage	V _F	7	I _F =350mA				2.0	V
Input Capacitance	CIN					15		pF
Turn-On Delay	t _{on}	8	V _{OUT} =50V, R _L =125Ω C _L =15pF			0.1		μs
Turn-Off Delay	t _{OFF}	8	V _{OUT} =50V, F C _L =15pF	R _L =125Ω		0.2		μs

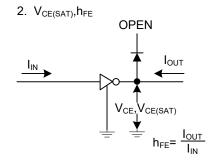
■ ELECTRICAL CHARACTERISTICS (T_A=25°C, unless otherwise specified)



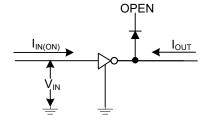
TEST CIRCUIT

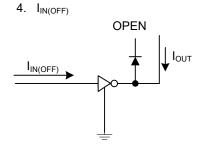
Components in the test circuits are used only to obtain and confirm the device characteristics. These components and circuits are not guaranteed to prevent malfunction or failure from occurring in the application equipment.



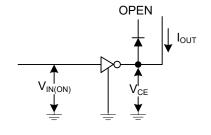


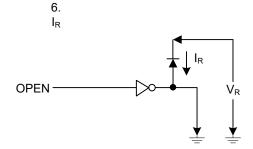








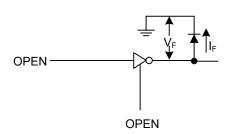




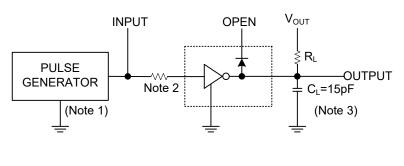


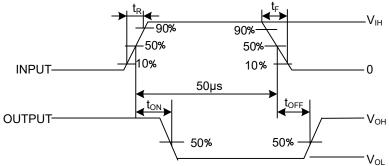
■ TEST CIRCUIT (Cont.)

7. V_F



 $8. \quad t_{\text{ON}}, \, t_{\text{OFF}}$





Notes: 1. Pulse width 50µs, duty cycle 10%, Output impedance 50 Ω , t_R ≤ 5ns, t_F ≤ 10ns. 2. See below.

INPUT CONDITION

Ī	TYPE NUMBER	R1	V _{IH}
	ULN2003	0	3V

3: C_L includes probe and jig capacitance.



APPLICATION NOTES

This UTC **ULN2003** has no protection functions for over-current and over-voltage. If the applied situation includes over-current or over-voltage, this IC may be destroyed. We should take care of the systems design with this IC. The OUTPUT, COMMON and GND lines should be designed carefully, because the IC may be destroyed due to short-circuit between outputs, air contamination fault, or fault by improper grounding.

The UTC **ULN2003** is a darlington driver array. When it is applied with a general logic circuit such as TTL or CMOS, resistors should be connected in series to every input to achieve a stable input current.

When the load is connected between the output and the power supply, the COMMON pin should be shorted to the power supply to protect the IC from extra swing voltage.

NOTICE ON PRODUCT USE

(1) The absolute maximum ratings should be not exceeded, even for a moment, otherwise the device may be breakdown, damaged or deteriorated, and even injury by explosion or combustion.

(2) The power supply fuse should be used to prevent a continuous large current from the over current situation and IC failure. The improper wiring layout and an abnormal pulse noise from the wiring or load both can cause a large continuous current and even the breakdown, and finally can lead smoke or ignition. So we should design carefully considering fuse capacity, fusing time and insertion circuit location, the effects of a large current can be improved.

(3) When the inductive load is applied such as motor coil, it can cause the device malfunction or breakdown due to the current resulting from the inrush current at power ON or the negative current resulting from the back electromotive force at power OFF, so a protection circuit should be designed. When using build-in protection functions IC, a stable power supply is required, otherwise the protection function may not operate and cause IC breakdown. IC breakdown may result injury, smoke or ignition.

(4) The devices should not be mounted in the wrong orientation or incorrectly, and the positive and negative terminals of power supplies should also are connected properly, otherwise the current or power consumption may exceed the absolute maximum rating, also it may cause the device breakdown, damage or deterioration, and may result injury by explosion or combustion. In addition, any device should not be used when it is applied the current with mounted in the wrong orientation or incorrectly even just one time.

(5) The careful selection of external components is also important, such as inputs and negative feedback capacitors, load components (such as speakers), power amp and regulator. If a large leakage current flow the input or negative feedback capacitors, the IC output DC voltage will be increased. If this output voltage is connected to a speaker with low input withstand voltage, the smoke or ignition can be caused for over-current or IC failure, even the smoke or ignition from the IC itself. In addition, please also pay attention to the Bridge Tied Load (BTL) connection type IC that inputs output DC voltage to a speaker directly.

POINTS TO REMEMBER ON PRODUCT USE

(1) Heat Dissipation Design

An inadequate IC heat dissipation design can reduce the IC life, deterioration of IC characteristics, even IC breakdown. When the IC is applied with a large current flow such as power amp, regulator and so on, the careful heat dissipation design should be implemented, not to exceed the maximum ratings of junction temperature (Tj). Meanwhile, also please pay attention to the effect of IC heat dissipation on peripheral components.

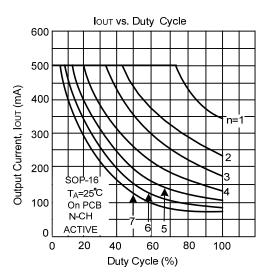
(2) Back-EMF

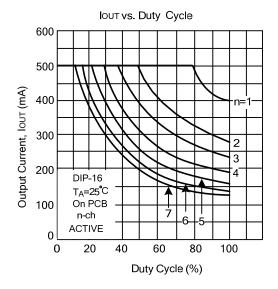
Being the effect of back-EMF, a current can flow back to the motor's power supply when a motor rotates in the reverse direction, stops or slows down suddenly. If the power supply has a low current sink capability, the device's motor power supply and output pins might be influenced for excessing the absolute maximum ratings. In the system design, we should take the effect of back-EMF into consideration to avoid the accident.

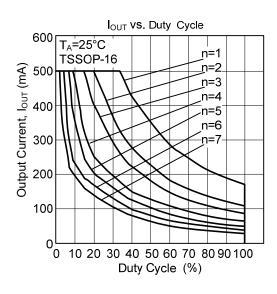


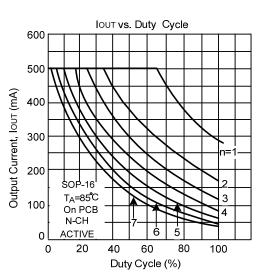
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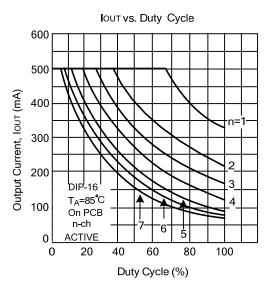
TYPICAL CHARACTERISTICS

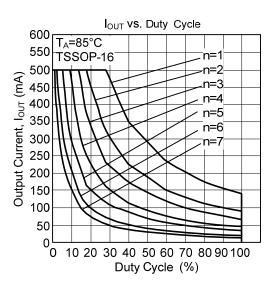








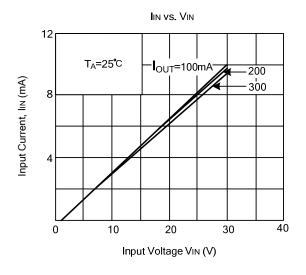


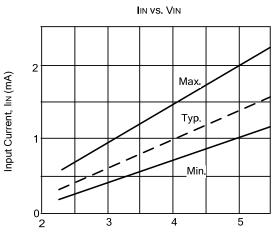




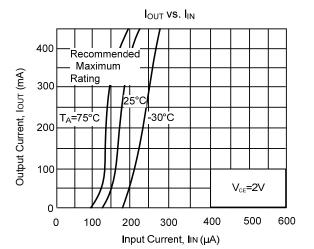
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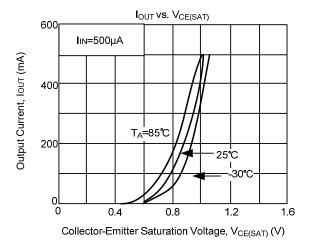
TYPICAL CHARACTERISTICS (Cont.)





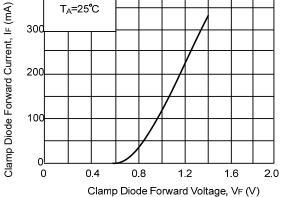






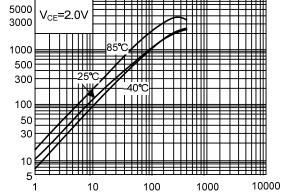
DC Current Transfer Ratio, hFE 10 5 10 100 1 IF VS.VF 400 T_A=25℃ 300

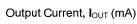
10000



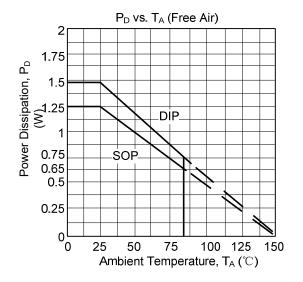


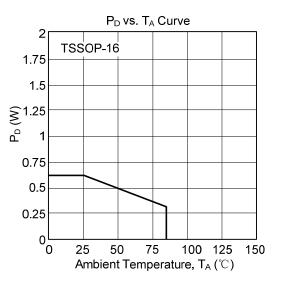
hfe vs. IOUT





■ TYPICAL CHARACTERISTICS (Cont.)





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